## Potential Theory and Nonlinear Elliptic Equations Lecture 2

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### Publications

- A. Grigor'yan and I. Verbitsky, Pointwise estimates of solutions to nonlinear equations for non-local operators, Ann. Scuola Norm. Super. Pisa, 20 (2020) 721–750
- A. Grigor'yan and I. Verbitsky, Pointwise estimates of solutions to semilinear elliptic equations and inequalities, J. D'Analyse Math., 137 (2019) 529–558
- 3 A. Grigor'yan and W. Hansen, Lower estimates for a perturbed Green function, J. D'Analyse Math., 104 (2008), 25–58.
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### Additional literature

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- A. Grigor'yan, Heat Kernel and Analysis on Manifolds, Amer. Math.Soc./Intern. Press Studies in Adv. Math., 47, 2009.
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### The Laplace-Beltrami operator

Recall that the gradient operator  $\boldsymbol{\nabla}$  is defined by

$$(\nabla u)^i = \sum_{j=1}^n g^{ij} \partial_{x_j} u.$$

The divergence operator  $\operatorname{div}$  on vector fields  $F^i$  is defined by

$$\operatorname{div} F = \frac{1}{\sqrt{\det g}} \sum_{i=1}^{n} \partial_{x_i} \left( \sqrt{\det g} F^i \right).$$

The Laplace-Beltrami operator  $\mathcal{L}_0$  is represented in the form

$$\mathcal{L}_0 = \operatorname{div} \circ \nabla.$$

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### The weighted Laplace operator

Let (M, m) be a weighted manifold with  $dm = \omega dm_0$ . The weighted divergence operator is defined by

$$\operatorname{div}_{\omega} = rac{1}{\omega} \circ \operatorname{div} \circ \omega.$$

Recall that  $\nabla$  and div are the Riemannian gradient and divergence, respectively, and do not depend on the weight  $\omega$ .

The (weighted) Laplace operator  $\mathcal{L} = \Delta$  is defined by  $\Delta = \operatorname{div}_{\omega} \circ \nabla$ . From the definitions of  $\nabla$  and  $\operatorname{div}$ , it follows that

$$\Delta u = \frac{1}{\omega} \operatorname{div} \left( \omega \nabla u \right) = \frac{1}{\omega \sqrt{\det g}} \sum_{i,j=1}^{n} \partial_{x_i} \left( \omega \sqrt{\det g} g^{ij} \partial_{x_j} u \right), \quad (1)$$

acting on  $C^2$  functions u on M.

Example (elliptic differential operators in  $\mathbb{R}^n$ )

In an open set  $\Omega \subseteq \mathbb{R}^n$  consider the operator

$$Lu = b(x) \sum_{i,j=1}^{n} \partial_{x_i} (a_{ij}(x) \partial_{x_j} u), \qquad (2)$$

where b,  $A = (a_{ij})$  are smooth functions, and b > 0.

We assume here that the matrix A(x) is symmetric and positive definite for any  $x \in \Omega$ .

In other words, the operator  $\boldsymbol{L}$  is elliptic (the uniform ellipticity is not needed).

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# Example (elliptic differential operators in $\mathbb{R}^n$ ) (continuation)

We claim that L coincides with the *weighted* Laplace operator  $\Delta$  on  $\Omega \subseteq \mathbb{R}^n$  with the Riemannian metric g and weight  $\omega$  chosen so that

$$\left(\boldsymbol{g}^{\boldsymbol{i}\boldsymbol{j}}\right) = \boldsymbol{b}\left(\boldsymbol{a}_{\boldsymbol{i}\boldsymbol{j}}\right), \qquad \omega = \boldsymbol{b}^{\frac{n}{2}-1}\sqrt{\det \boldsymbol{A}}.$$
 (3)

Clearly,

$$\det g = \det (g_{ij}) = \frac{1}{b^n \det A}.$$
 (4)

The measure  $dm = \omega dm_0$  associated with  $\Delta$  is given by

$$dm = \omega \sqrt{\det g} \, dx = b^{\frac{n}{2}-1} \sqrt{\det A} \frac{1}{\sqrt{b^n \det A}} \, dx = \frac{1}{b} \, dx, \quad (5)$$

where dx is Lebesgue measure.

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# Example (elliptic differential operators in $\mathbb{R}^n$ ) (continuation)

Recall that by (1), we have

$$\Delta u = \frac{1}{\omega \sqrt{\det g}} \sum_{i,j=1}^{n} \partial_{x_i} \left( \omega \sqrt{\det g} g^{ij} \partial_{x_j} u \right).$$
(6)

Substituting (3), (4) into (6) yields

$$\Delta u = \frac{\sqrt{b^n \det A}}{b^{\frac{n}{2}-1}\sqrt{\det A}} \sum_{i,j=1}^n \partial_{x_i} \left( b^{\frac{n}{2}-1}\sqrt{\det A} \frac{1}{\sqrt{b^n \det A}} b a^{ij} \partial_{x_j} u \right)$$
$$= b \sum_{i,j=1}^n \partial_{x_i} \left( a_{ij} \left( x \right) \partial_{x_j} u \right) = Lu.$$

Therefore, the results below for a general weighted manifold (M, m), are applicable to the operator L in  $\Omega \subset \mathbb{R}^n$  with the measure m. In particular, if  $b \equiv 1$ , then  $L = \operatorname{div}(A\nabla \cdot)$  and m is Lebesgue measure.

### The Doob transform

Given a positive  $C^2$  function h in  $\Omega \subseteq M$ , consider the following operator,

$$L^h = rac{1}{h} \circ \Delta \circ h$$

acting on  $C^2(\Omega)$ . The operator  $L^h$  is called the Doob transform of  $\Delta$ . Usually it is used for harmonic functions h, but we use  $L^h$  for **superharmonic** h as well [Grigor'yan-Verbitsky 2019]. Notice that  $L^h$  can be written in the form

$$L^{h}v = \Delta^{h}v + \frac{\Delta h}{h}v, \qquad (7)$$

where  $\mathbf{v} \in C^2(\Omega)$  and  $\Delta^h$  is the *h*-Laplacian defined by

$$\Delta^{h} \boldsymbol{v} = \frac{1}{h^{2}} \operatorname{div}_{\omega} (h^{2} \nabla \boldsymbol{v}). \tag{8}$$

Note that  $\Delta^h$  is the Laplace operator for the measure  $h^2 dm = h^2 \omega dm_0$ .

### Green functions

Recall that, for a general weight  $\omega$ , the Laplace operator  $\mathcal{L} = \Delta$  is *symmetric* with respect to the measure m. Moreover,  $\Delta$  satisfies the Chain Rule and the Product Rule, like in the case  $\omega = 1$ , when  $\Delta = \mathcal{L}_0$  is the Laplace-Beltrami operator.

For any open connected set  $\Omega \subseteq M$ , we denote by  $G^{\Omega}(x, y)$  the infimum of all positive fundamental solutions of  $\Delta$  in  $\Omega$ .

Then the following is true:

either  $G^{\Omega}(x,y) \equiv +\infty$  or  $G^{\Omega}(x,y) < +\infty$  for all  $x \neq y$ .

In the latter case we will say that  $G^{\Omega}$  is **non-trivial**, and call  $G^{\Omega}$  the **minimal Green function** (positive, symmetric) of  $\Delta$  in  $\Omega$ .

The existence of a non-trivial  $G^{\Omega}$  is the only assumption on  $\Omega$  that we impose.

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## Green potentials

If  $G^{\Omega}$  is the non-trivial minimal Green function, then for any  $\mu \in \mathcal{M}^+(\Omega)$ , the Green potential  $G^{\Omega}\mu$  is defined by

$$\mathrm{G}^{\Omega}\mu(x) = \int_{\Omega} \boldsymbol{G}^{\Omega}(x, y) \, d\mu(y) \, .$$

For a nonnegative  $f \in L^1_{loc}(\Omega, m)$ , we set  $G^{\Omega}f := G^{\Omega}(f dm)$ . For a signed function  $f \in L^1_{loc}(\Omega, m)$ ,

$$\mathrm{G}^{\Omega}f\left(x\right)=\mathrm{G}^{\Omega}f_{+}\left(x\right)-\mathrm{G}^{\Omega}f_{-}\left(x\right)$$

assuming at least one of the following:

$$G^{\Omega}f_{+}(x) < +\infty, \text{ or } G^{\Omega}f_{-}(x) < +\infty.$$
  
Then  $G^{\Omega}f(x)$  is said to be *well-defined*.  
**Remark.** If  $\Omega$  is relatively compact then  $G^{\Omega}$  is non-trivial,  
 $G^{\Omega}(x, \cdot) \in L^{1}(\Omega)$ , and  $G^{\Omega}f$  is finite for any  $f \in L^{\infty}(\Omega)$ .

## Local case: semi-linear inequalities

#### (with boundary conditions)

Our main goal is to obtain "sharp" pointwise estimates of positive sub/super-solutions to the following model semi-linear problem.

Problem. Let  $\Omega \subset M$  be an open relatively compact connected subdomain of M. Given  $V \in C(\overline{\Omega})$ ,  $\mu \in C(\overline{\Omega})$ ,  $\nu \in C(\partial\Omega)$ ,  $\mu, \nu \geq 0$ , assume that there exists a *nonnegative* solution u to the following semi-linear Dirichlet problem:

$$\begin{cases} -\Delta u + V u^{q} \ge \mu & \text{ in } \Omega \\ u \ge \nu & \text{ in } \partial \Omega, \end{cases}$$
(9)

if  $\boldsymbol{q} > \boldsymbol{0}$ , and

$$\begin{cases} -\Delta u + V u^{q} \leq \mu & \text{ in } \Omega \\ u \leq \nu & \text{ in } \partial \Omega, \end{cases}$$
(10)

if q < 0. **Remark.** Here  $u \in C^2(\Omega) \cap C(\overline{\Omega})$  is a *classical* solution.

### The auxiliary linear Dirichlet problem

**Remark.** Analogues for **general** domains  $\Omega \subseteq M$  (not necessarily relatively compact) and **non-smooth** coefficients/data are discussed below.

We will compare  $\boldsymbol{u}$  to the solution  $\boldsymbol{h}$  of the following *auxiliary* linear Dirichlet problem:

$$egin{cases} -\Delta h = \mu & ext{ in } \Omega, \ h = 
u & ext{ in } \partial \Omega, \end{cases}$$

where  $h \ge 0$  is *superharmonic* in  $\Omega$  ( $\mu, \nu \ge 0$ ), for regular domains  $\Omega$ . We will write

$$h = \mathbf{P}^{\Omega} \nu + \mathbf{G}^{\Omega} \mu.$$

For smooth domains  $\mathbf{P}^{\Omega}\nu$  and  $\mathbf{G}^{\Omega}\mu$  are given by the Poisson and Green integrals respectively.

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### Main results: local case

#### Theorem 3 (Grigor'yan-Verbitsky 2019)

Let (M, m) be a weighted manifold,  $\Omega \subset M$  an open relatively compact subdomain of M,  $\partial \Omega$  regular,  $V \in C(\overline{\Omega})$ ,  $\mu \in C(\overline{\Omega})$ ,  $\nu \in C(\partial \Omega)$ ,  $\mu, \nu \geq 0$ ,  $\mu$  locally Hölder continuous, either  $\mu \not\equiv 0$  or  $\nu \not\equiv 0$ , which ensures that h > 0 in  $\Omega$ . Suppose  $u \in C^2(\Omega) \cap C(\overline{\Omega})$  is a non-negative super-solution to (9) if q > 0, or sub-solution to (10) if q < 0. Then the following statements hold for all  $x \in \Omega$ . (i) If q = 1, then

$$u(x) \geq h(x)e^{-\frac{1}{h(x)}G^{\Omega}(hV)(x)}.$$
 (11)

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Main results: local case (continuation)

Theorem 3 (statements (ii), (iii))

(ii) If q > 1, then necessarily the condition

$$-(q-1) \operatorname{G}^{\Omega}(h^{q} V)(x) < h(x)$$
(12)

holds in  $\Omega$ , and

$$u(x) \ge h(x) \left[ 1 + (q-1) \frac{G^{\Omega}(h^{q}V)(x)}{h(x)} \right]^{-\frac{1}{q-1}}$$
. (13)

(iii) If 0 < q < 1, then

$$u(x) \geq h(x) \left[1 - (1-q) \frac{\mathrm{G}^{\Omega}(\chi_{\Omega^+} h^q \mathbf{V})(x)}{h(x)}\right]_+^{\frac{1}{1-q}}, \qquad (14)$$

where  $\Omega^+ = \{x \in \Omega : u(x) > 0\}$ .

# Main results: local case (continuation)

Theorem 3 (statement (iv))

(iv) If q < 0 and u > 0 in  $\Omega$  then necessarily the condition

$$(1-q) \operatorname{G}^{\Omega}(h^{q} V)(x) < h(x), \qquad (15)$$

holds in  $\Omega$ , and

$$u(x) \leq h(x) \left[1 - (1-q) \frac{\mathrm{G}^{\Omega}(h^q V)(x)}{h(x)}\right]^{\frac{1}{1-q}}, \qquad (16)$$

provided  $G^{\Omega}(h^{q}V)(x)$  is well-defined.

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Inequalities for  $L^h v$ ;  $v = \phi^{-1} \left(\frac{u}{h}\right)$ ,  $\phi$  increasing

Lemma (inequalities for the Doob transform)

Let **h** be a positive  $C^2$ -function in  $\Omega$ . Let **u** be a solution of

$$-\Delta u + V u^q \ge -\Delta h \tag{17}$$

in  $\Omega$ , where  $V \in C(\Omega)$  and  $q \in \mathbb{R} \setminus \{0\}$ . Let  $\phi$  be a  $C^2$  function on an interval  $I \subset \mathbb{R}$  such that  $\phi' > 0$  in I. Assume  $\frac{u}{h}(\Omega) \subset \phi(I)$ . Then  $v = \phi^{-1}(\frac{u}{h})$  satisfies the differential inequality:

$$-L^{h}\boldsymbol{v} + h^{q-1}\boldsymbol{V}\frac{\phi(\boldsymbol{v})^{q}}{\phi'(\boldsymbol{v})} \geq L^{h}\mathbf{1}\left(\frac{\phi(\boldsymbol{v})-1}{\phi'(\boldsymbol{v})}-\boldsymbol{v}\right) + \frac{\phi''(\boldsymbol{v})}{\phi'(\boldsymbol{v})}|\nabla\boldsymbol{v}|^{2}.$$
 (18)

If in place of (17) we have

$$-\Delta u + V u^q \le -\Delta h, \tag{19}$$

then (18) holds with  $\leq$  instead of  $\geq$ .

## Proof of the lemma Recall that $L^{h} = \frac{1}{h} \circ \Delta \circ h$ . In particular, $L^{h}1 = \frac{\Delta h}{h}$ . Set $\tilde{u} = \frac{u}{h}$ , so that $L^{h}\tilde{u} = \frac{1}{h}\Delta u$ . Divide both sides of (17) by h: $-L^{h}\tilde{u} + h^{q-1}V\tilde{u}^{q} \ge -L^{h}1.$ (20)

By the Chain Rule, for any  $\boldsymbol{v} \in \boldsymbol{C}^2\left(\Omega\right)$ 

$$\Delta^h \phi(\mathbf{v}) = \phi'(\mathbf{v}) \Delta^h \mathbf{v} + \phi''(\mathbf{v}) |\nabla \mathbf{v}|^2.$$

By (7) applied to  $\tilde{u} = \phi(v)$ , we have  $L^h \tilde{u} = \Delta^h \tilde{u} + \frac{\Delta h}{h} \tilde{u}$ . Hence,

$$\begin{split} L^{h}\phi(\mathbf{v}) &= \Delta^{h}\phi(\mathbf{v}) + \frac{\Delta h}{h}\phi(\mathbf{v}) \\ &= \phi'(\mathbf{v})\Delta^{h}\mathbf{v} + \phi''(\mathbf{v})|\nabla \mathbf{v}|^{2} + \frac{\Delta h}{h}\phi(\mathbf{v}) \\ &= \phi'(\mathbf{v})(\Delta^{h}\mathbf{v} + \frac{\Delta h}{h}\mathbf{v}) + \phi''(\mathbf{v})|\nabla \mathbf{v}|^{2} + \frac{\Delta h}{h}\left(\phi(\mathbf{v}) - \mathbf{v}\phi'(\mathbf{v})\right) \\ &= \phi'(\mathbf{v})L^{h}\mathbf{v} + \phi''(\mathbf{v})|\nabla \mathbf{v}|^{2} + \frac{\Delta h}{h}\left(\phi(\mathbf{v}) - \mathbf{v}\phi'(\mathbf{v})\right). \end{split}$$

### End of the proof

Therefore, solving for  $L^h v$ , we have

$$-L^{h}\boldsymbol{v} = -\frac{L^{h}\phi(\boldsymbol{v})}{\phi'(\boldsymbol{v})} + \frac{\phi''(\boldsymbol{v})}{\phi'(\boldsymbol{v})}|\nabla\boldsymbol{v}|^{2} + \frac{\Delta h}{h}\left(\frac{\phi(\boldsymbol{v})}{\phi'(\boldsymbol{v})} - \boldsymbol{v}\right). \quad (21)$$

Since  $\tilde{u} = \phi(v)$ , it follows that (20) yields the following estimate:

$$-L^h\phi(\mathbf{v})+h^{q-1}V\phi(\mathbf{v})^q\geq-L^h\mathbf{1}.$$

Substituting this inequality into (21), we get rid of  $L^{h}\phi(v)$ :

$$-L^{h}v+h^{q-1}V\frac{\phi(v)^{q}}{\phi'(v)}\geq L^{h}1\left(\frac{\phi(v)-1}{\phi'(v)}-v\right)+\frac{\phi''(v)}{\phi'(v)}|\nabla v|^{2}.$$

This proves the desired inequality for  $L^h v$ . The converse inequality with  $\leq$  in place  $\geq$  is proved in the same way.

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Inequalities for 
$$\Delta(hv)$$
;  $v = \phi^{-1}\left(\frac{u}{h}\right)$ 

 $\phi$  increasing, convex

#### Corollary (superharmonic **h**)

Under the hypotheses of the Lemma, assume in addition  $\Delta h \leq 0$  in  $\Omega$ and  $0 \in I$ . (i) If  $\phi$  is convex in the interval I, so that

$$\phi(0) = 1, \quad \phi' > 0, \quad \phi'' \ge 0,$$
 (22)

and **u** satisfies  $-\Delta u + Vu^q \ge -\Delta h$ , then the function  $\mathbf{v} = \phi^{-1} \left(\frac{u}{h}\right)$  satisfies the following inequality in  $\Omega$ :

$$-\Delta (hv) + h^q V \frac{\phi(v)^q}{\phi'(v)} \ge 0.$$
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Inequalities for  $\Delta(hv)$ ;  $v = \phi^{-1}(\frac{u}{h})$ 

 $\phi$  increasing, concave

Corollary (superharmonic h) (ii) If  $\phi$  is concave in the interval I, so that  $\phi(0) = 1, \quad \phi' > 0, \quad \phi'' \le 0,$  (24) and u satisfies  $-\Delta u + Vu^q \le -\Delta h$ , then v satisfies  $-\Delta (hv) + h^q V \frac{\phi(v)^q}{\phi'(v)} \le 0.$  (25)

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### Proof of the corollary

To prove (i), notice that, for a convex  $\phi$  such that  $\phi' > 0$ ,  $\phi(0) = 1$ ,

$$rac{\phi({m v})-1}{\phi'({m v})}-{m v}\geq {m 0},$$

since the chord of the graph of the convex function  $\phi$  between the points (0,1) and  $(v,\phi(v))$  lies above the tangent line at  $(v,\phi(v))$ . Using also that  $L^h 1 = \frac{\Delta h}{h} \leq 0$ , we obtain from the Lemma:

$$-L^h v + h^{q-1} V rac{\phi(v)^q}{\phi'(v)} \geq 0,$$

which is equivalent to (23), since  $\Delta(hv) = h L^h v$ . The proof of statement (ii) is similar.

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## A comparison principle for superharmonic functions

The following two lemmas enable us to get rid of some technical assumptions like  $\inf_{\Omega} h > 0$  initially used in the proofs below.

#### Lemma (a comparison principle)

Suppose  $\Omega \subseteq M$  is open, and F is a superharmonic function in  $\Omega$ . Suppose  $F = F_1 + F_2$  where  $\liminf_{x\to z} F_1(x) \ge 0$  for every  $z \in \partial_{\infty} \Omega$ , and  $F_2 \ge -P$ , where  $P = G^{\Omega} \mu$  is a Green potential of a positive measure  $\mu$  in  $\Omega$ ,  $P \not\equiv +\infty$  on every component of  $\Omega$ . Then  $F \ge 0$  in  $\Omega$ .

#### Proof.

The function F + P is obviously superharmonic, and  $F + P \ge F_1$ . Hence  $\liminf_{x\to z} (F + P)(x) \ge 0$  for  $z \in \partial_{\infty} \Omega$ , and by the maximum principle  $F + P \ge 0$  on  $\Omega$ . Hence F is a superharmonic majorant of -P, whose least superharmonic majorant must be zero, which yields  $F \ge 0$ .

**Remark.** The case P = 0 gives the usual form of the maximum principle.

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## A version of the maximum principle

The following version of the maximum principle will be frequently used below. It is deduced from the previous comparison lemma.

#### Lemma (a maximum principle)

Let  $\Omega$  be an open subset of M with non-trivial Greeen's function, and let  $v \in C^2(\Omega)$  satisfy

$$\begin{cases} -\Delta v \ge f & \text{in } \Omega_{x} \\ \liminf_{x \to \partial_{\infty} \Omega} v(x) \ge 0, \end{cases}$$

where  $f \in C(\Omega)$  such that  $G^{\Omega}f$  is well defined in  $\Omega$ . Then

$$\mathbf{v}(\mathbf{x}) \geq \mathbf{G}^{\Omega} f(\mathbf{x}), \quad \forall \mathbf{x} \in \Omega.$$
 (26)

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# Semi-linear problems in "nice" domains under the assumption $\inf_{\Omega} h > 0$

#### Lemma (proof of Theorem 3: $\inf_{\Omega} h > 0$ , smooth boundary)

Suppose  $\Omega$  is a relatively compact domain in M with smooth boundary. Suppose  $u \in C^2(\Omega) \cap C(\overline{\Omega})$ ,  $V \in C(\overline{\Omega})$ , and  $\mu$ ,  $\nu$  are non-negative functions such that  $\nu \in C(\partial\Omega)$ , and  $\mu \in C(\overline{\Omega}) \cap C^{\alpha}(\Omega)$  for some  $\alpha \in (0, 1]$ . Let

$$\boldsymbol{h} = \mathbf{P}^{\Omega} \boldsymbol{\nu} + \mathbf{G}^{\Omega} \boldsymbol{\mu}. \tag{27}$$

If  $\inf_{\Omega} h > 0$ , then the following statements hold. (i) In the case q > 0, if u > 0 is a solution of

$$\begin{cases} -\Delta u + V u^{q} \ge \mu & \text{ in } \Omega, \\ u \ge \nu & \text{ in } \partial \Omega, \end{cases}$$
(28)

then statements (i)-(iii) of Theorem 3 are valid (lower bounds for  $\mathbf{u}$ ).

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# Semi-linear problems in "nice" domains under the assumption $\inf_{\Omega} h > 0$

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Lemma (continuation)
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(ii) In the case q < 0, if u > 0 is a solution of

$$egin{cases} -\Delta u + V u^q \leq \mu & ext{ in } \Omega, \ u \leq 
u & ext{ in } \partial \Omega \end{cases}$$

then statement (iv) of Theorem 3 is valid (upper bounds for u).

**Remarks.** 1. The technical assumption  $\inf_{\Omega} h > 0$  is removed using the maximum principle lemma stated above.

2. The restriction that  $\Omega$  has a smooth boundary is unnecessary, and will be removed below.

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### Proof of the Lemma

By the hypotheses,  $h \in C^2(\Omega)$ ,  $-\Delta h = \mu$ , and h > 0 in  $\Omega$ . Choose the function  $\phi$  in the Corollary to satisfy the equation

$$\phi'(\mathbf{v}) = \phi(\mathbf{v})^q. \tag{30}$$

For q = 1, this gives

$$\phi(\mathbf{v}) = \mathbf{e}^{\mathbf{v}}, \quad \mathbf{v} \in \mathbb{R}, \tag{31}$$

while for  $q \neq 1$ , we obtain

$$\phi(\mathbf{v}) = [(1-q)\mathbf{v}+1]^{\frac{1}{1-q}}, \quad \mathbf{v} \in \mathbf{I}_q, \tag{32}$$

where the domain  $I_q$  of  $\phi$  is given by:

$$I_{q} = \begin{cases} \left(-\frac{1}{1-q}, +\infty\right) & \text{if } q < 1, \\ \left(-\infty, +\infty\right) & \text{if } q = 1, \\ \left(-\infty, \frac{1}{q-1}\right) & \text{if } q > 1. \end{cases}$$
(33)

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### Proof of the Lemma

(continuation)

Note that in all cases  $\phi(I_q) = (0, \infty)$ . Also, we have

$$\phi'(\mathbf{v}) = [(1-q)\mathbf{v}+1]^{\frac{q}{1-q}}, \quad \phi''(\mathbf{v}) = q[(1-q)\mathbf{v}+1]^{\frac{2q-1}{1-q}}.$$
 (34)

Since  $u = h\phi(v)$ , all the estimates in the case q > 0 follow from:

$$v(x) \ge -\frac{1}{h(x)} G^{\Omega}(h^q V)(x)$$
 for all  $x \in \Omega$ . (35)

For q < 0, we will have the opposite inequality. Let us use the function hv expressed explicitly via u and h as follows:

$$hv = \begin{cases} \frac{1}{q-1}h\left(1-(\frac{h}{u})^{q-1}\right) & \text{if } 1 < q < +\infty, \\ h\log(\frac{u}{h}) & \text{if } q = 1, \\ \frac{1}{1-q}\left(h^{q}u^{1-q} - h\right) & \text{if } -\infty < q < 1. \end{cases}$$
(36)

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### Proof of the Lemma

(continuation)

Since u > 0, h > 0 in  $\Omega$ , we have  $\frac{u}{h}(\Omega) \subset \phi(I_q) = (0, \infty)$ , and  $hv \in C^2(\Omega)$ .

In the case q > 0 the function  $\phi$  is concave, increasing, and  $\phi(0) = 1$ . We obtain from the Corollary,

$$-\Delta (hv) + h^q V \ge 0. \tag{37}$$

Since  $u \ge \nu > 0$  on  $\partial \Omega$ , and consequently  $\inf_{\Omega} u > 0$ , we actually have  $hv \in C(\overline{\Omega}) \cap C^2(\Omega)$ , and  $hv \ge 0$  on  $\partial \Omega$ , which by the maximum principle implies (35). In addition, if q > 1, then  $l_q = (-\infty, \frac{1}{q-1})$ , so that  $v(x) < \frac{1}{q-1}$ . Combining this estimate with (35) gives the **necessary** condition for the existence of u:

$$-\mathrm{G}^{\Omega}(h^{q}V)(x) < rac{1}{q-1}h(x), ext{ for all } x \in \Omega.$$

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# Proof of the Lemma (continuation)

Similarly, in the case q < 0, we have  $hv \in C(\overline{\Omega}) \cap C^2(\Omega)$  since  $\inf_{\Omega} h > 0$ . The inequality  $u \leq \nu$  on  $\partial \Omega$  yields the boundary condition  $hv \leq 0$  on  $\partial \Omega$ . By the Corollary we obtain that in  $\Omega$ ,

$$-\Delta (hv) + h^q V \leq 0, \quad \text{for all } x \in \Omega.$$
 (38)

Together with the boundary condition this yields by the maximum principle

$$v(x) \leq -\frac{1}{h(x)} G^{\Omega}(h^q V)(x), \text{ for all } x \in \Omega.$$
 (39)

In view of (36), this translates into the desired inequality (16) for u. Moreover, since  $I_q = \left(-\frac{1}{1-q}, +\infty\right)$ , in this case  $v(x) > -\frac{1}{1-q}$ . Combining this estimate with (39) yields the **necessary** condition (15) for the existence of u, namely  $(1-q)G^{\Omega}(h^q V)(x) < h(x)$ ,  $\forall x \in \Omega$ .

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### Proof of Theorem 3

Suppose  $\Omega \subset M$  is a relatively compact domain whose boundary is regular with respect to the Dirichlet problem. Let

$$\boldsymbol{h} = \boldsymbol{P}^{\Omega} \boldsymbol{\nu} + \mathbf{G}^{\Omega} \boldsymbol{\mu} > \boldsymbol{0} \quad \text{in } \boldsymbol{\Omega}.$$
 (40)

Since  $\mu$  is uniformly bounded in  $\Omega$ , we have

$$\mathrm{G}^{\Omega}\mu\leq(\sup_{\Omega}\mu)\,\mathrm{G}^{\Omega}\mathbf{1},$$

and hence by the regularity of  $\partial \Omega$ ,

$$\lim_{y\to x} \mathrm{G}^{\Omega}\mu(y) = \lim_{y\to x} \mathrm{G}^{\Omega}\mathbf{1}(y) = \mathbf{0}, \quad \lim_{y\to x} P^{\Omega}\nu(y) = \nu(x), \quad x\in\partial\Omega.$$

It follows  $h \in C^2(\Omega) \cap C(\overline{\Omega})$ ,  $-\Delta h = \mu$ , and

$$\lim_{y\to x}h(y)=\lim_{y\to x}u(y)=\nu(x), \quad x\in\partial\Omega.$$

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For  $\epsilon > 0$ , set  $u_{\epsilon} = u + \epsilon$ ,  $h_{\epsilon} = h + \epsilon$ , and define the function  $v_{\epsilon}$  via

$$\frac{u_{\epsilon}}{h_{\epsilon}} = \phi(v_{\epsilon}),$$

where  $\phi$  is chosen as in the proof of the previous Lemma. Note that  $h_{\epsilon} > 0$  is superharmonic in  $\Omega$ , and  $-\Delta h_{\epsilon} = \mu$ . Clearly,  $h_{\epsilon}, u_{\epsilon}, v_{\epsilon} \in C^{2}(\Omega) \cap C(\overline{\Omega})$ . Identity (21) applied to  $h_{\epsilon}, u_{\epsilon}, v_{\epsilon}$  in place of h, u, v gives

$$-\Delta(h_{\epsilon}\mathbf{v}_{\epsilon}) = \frac{-\Delta u}{\phi'(\mathbf{v}_{\epsilon})} + \frac{\phi''(\mathbf{v}_{\epsilon})}{\phi'(\mathbf{v}_{\epsilon})}|\nabla \mathbf{v}|^{2}h_{\epsilon} + \Delta h\left(\frac{\phi(\mathbf{v}_{\epsilon})}{\phi'(\mathbf{v}_{\epsilon})} - \mathbf{v}_{\epsilon}\right),$$

where

$$\phi'(\mathbf{v}_{\epsilon}) = \phi(\mathbf{v}_{\epsilon})^{\mathbf{q}} = \left(\frac{u_{\epsilon}}{h_{\epsilon}}\right)^{\mathbf{q}}$$

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Proof of Theorem 3 (continuation)  
Suppose 
$$q > 0$$
 and  $-\Delta u \ge -Vu^q + \mu$ ,  $\mu = -\Delta h$ . Hence,  
 $-\Delta(h_{\epsilon}v_{\epsilon}) \ge -h_{\epsilon}^q \left(\frac{u}{u_{\epsilon}}\right)^q V + \frac{\phi''(v_{\epsilon})}{\phi'(v_{\epsilon})} |\nabla v|^2 h_{\epsilon} + \Delta h \left(\frac{\phi(v_{\epsilon}) - 1}{\phi'(v_{\epsilon})} - v_{\epsilon}\right).$ 

Drop the last two non-negative terms on the right:

$$-\Delta(h_{\epsilon}v_{\epsilon})+h_{\epsilon}^{q}\left(rac{u}{u_{\epsilon}}
ight)^{q}V\geq0.$$

Hence, the function

$$h_{\epsilon}v_{\epsilon} + G^{\Omega}\left(h_{\epsilon}^{q}\left(\frac{u}{u_{\epsilon}}\right)^{q}V\right)$$

is superharmonic in  $\Omega$ , and has non-negative boundary values:

$$h_{\epsilon}v_{\epsilon} = (
u + \epsilon)\phi^{-1}\left(rac{u+\epsilon}{
u+\epsilon}
ight) \geq (
u+\epsilon)\phi^{-1}(1) = 0 \quad ext{on } \partial\Omega,$$

since  $u \geq \nu$  on  $\partial \Omega$ ,  $\phi$  is increasing, and  $\phi(0) = 1$ ,

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Consequently, by the maximum principle lemma,

$$h_{\epsilon} v_{\epsilon} \geq -G^{\Omega} \left( h_{\epsilon}^{q} \left( \frac{u}{u_{\epsilon}} \right)^{q} V \right) \quad \text{in } \Omega.$$
 (41)

Since  $u \leq u_{\epsilon}$ , this implies

$$\boldsymbol{h}_{\epsilon}\boldsymbol{v}_{\epsilon} \geq -\mathbf{G}^{\Omega}\left(\boldsymbol{h}_{\epsilon}^{\boldsymbol{q}}\boldsymbol{V}_{+}\right), \qquad (42)$$

where, in the case  ${m q}>1$  we additionally have

$$-\frac{\mathrm{G}^{\Omega}\left(h_{\epsilon}^{q}\boldsymbol{V}_{+}\right)}{h_{\epsilon}} \leq -\frac{\mathrm{G}^{\Omega}\left(h_{\epsilon}^{q}\left(\frac{\boldsymbol{u}}{\boldsymbol{u}_{\epsilon}}\right)^{q}\boldsymbol{V}\right)}{h_{\epsilon}} \leq \boldsymbol{v}_{\epsilon} < \frac{1}{q-1}.$$
 (43)

Let us show that in the case  $q \ge 1$  actually u > 0 in  $\Omega$ . In terms of  $u_{\epsilon}$ , estimate (42) gives, for  $q \ge 1$ ,

$$\boldsymbol{u}_{\epsilon} \geq \boldsymbol{h}_{\epsilon}(\boldsymbol{x})\boldsymbol{\phi}\left(-\frac{\mathbf{G}^{\Omega}\left(\boldsymbol{h}_{\epsilon}^{\boldsymbol{q}}\boldsymbol{V}_{+}\right)}{\boldsymbol{h}_{\epsilon}}\right). \tag{44}$$

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Clearly,  $h_{\epsilon} \downarrow h$ , where h > 0 by (40). Passing to the limit as  $\epsilon \to 0$ , we deduce by the dominated convergence theorem, for  $q \ge 1$ ,

$$u \geq h\phi\left(-rac{\mathrm{G}^{\Omega}\left(h^{q}V_{+}
ight)}{h}
ight) > 0 \quad ext{in } \Omega.$$

Note that here, for q > 1, we have a strict inequality

$$-rac{\mathrm{G}^{\Omega}\left(h^{q}V_{+}
ight)\left(x
ight)}{h(x)}<rac{1}{q-1},$$

since otherwise  $u(x) = +\infty$ .

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Hence, in the case  $q \ge 1$ , we have u > 0 in  $\Omega$ . Consequently  $\frac{u}{u_{\epsilon}} \uparrow 1$  as  $\epsilon \downarrow 0$ , and by the dominated convergence theorem,

$$\lim_{\epsilon \to 0} \mathbf{G}^{\Omega} \left( \boldsymbol{h}_{\epsilon}^{\boldsymbol{q}} \left( \frac{\boldsymbol{u}}{\boldsymbol{u}_{\epsilon}} \right)^{\boldsymbol{q}} \boldsymbol{V} \right) = \mathbf{G}^{\Omega} \left( \boldsymbol{h}^{\boldsymbol{q}} \boldsymbol{V} \right).$$
(45)

The main estimate restated in terms of  $u_{\epsilon}$ :

$$u_{\epsilon} \geq h_{\epsilon}(x)\phi\Big(-\frac{\mathbf{G}^{\Omega}\left(h_{\epsilon}^{q}\left(\frac{u}{u_{\epsilon}}\right)^{q}V\right)}{h_{\epsilon}}\Big), \qquad (46)$$

where by (43) the right-hand side is well-defined. Passing to the limit as  $\epsilon \downarrow \mathbf{0}$ , we deduce, for  $\mathbf{q} \ge \mathbf{1}$ ,

$$u \geq h\phi\Big(-rac{\mathrm{G}^{\Omega}\left(h^{q}V
ight)}{h}\Big).$$

For  $\boldsymbol{q} > \boldsymbol{1}$ , additionally,

$$-\frac{\mathrm{G}^{\Omega}\left(h^{q}V\right)}{h} < \frac{1}{q-1}.$$

A similar argument applies for 0 < q < 1, but in this case u can be equal to zero on an open set, so that  $\frac{u}{u_{\epsilon}} \uparrow \chi_{\Omega^+}$  as  $\epsilon \downarrow 0$ . Passing to the limit in (41) using the dominated convergence theorem as above gives

$$h \mathbf{v} \geq - \mathrm{G}^{\Omega} \left( \chi_{\Omega^+} h^q \mathbf{V} 
ight),$$

which is equivalent to the desired lower estimate for  $\boldsymbol{u}$ .

In the case q < 0, we define the function  $v_{\epsilon}$  in a slightly different way, via the equation

$$\frac{u}{h_{\epsilon}} = \phi(\mathbf{v}_{\epsilon}),$$

where as before  $h_{\epsilon} = h + \epsilon$ , so that  $-\Delta h_{\epsilon} = \mu$ , and

$$h_{\epsilon} v_{\epsilon} = \frac{1}{1-q} h_{\epsilon}^{q} \left( u^{1-q} - h_{\epsilon}^{1-q} \right) \in C^{2}(\Omega) \cap C(\overline{\Omega}).$$
(47)

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Then

$$-\Delta(h_\epsilon v_\epsilon) + h_\epsilon^q V \leq 0.$$

Since  $\pmb{u} \leq \pmb{
u}$  on  $\partial \pmb{\Omega}$ , it follows

$$h_{\epsilon}v_{\epsilon}=rac{1}{1-q}\left(
u+\epsilon
ight)^{q}\left(u^{1-q}-(
u+\epsilon)^{1-q}
ight)\leq0$$
 on  $\partial\Omega.$ 

Hence,

$$h_{\epsilon} v_{\epsilon} \leq -\mathbf{G}^{\Omega}(h_{\epsilon}^{q} V) \quad \text{in } \Omega,$$
(48)

or, equivalently,

$$u \leq h_{\epsilon} \left[1-(1-q) \frac{\mathrm{G}^{\Omega}(h_{\epsilon}^{q} \mathsf{V})}{h_{\epsilon}}\right]^{\frac{1}{1-q}}$$
 in  $\Omega$ . (49)

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From the above estimates we deduce

$$-\frac{\mathrm{G}^{\Omega}(h_{\epsilon}^{q}V)}{h_{\epsilon}} \geq v_{\epsilon} > -\frac{1}{1-q}, \qquad (50)$$

so that the expression in square brackets in is always positive. Moreover,

$$-\frac{\mathrm{G}^{\Omega}(h_{\epsilon}^{q}V_{+})}{h_{\epsilon}}+\frac{\mathrm{G}^{\Omega}(h^{q}V_{-})}{h}>-\frac{1}{1-q}.$$
(51)

Since q < 0, we have  $h_{\epsilon}^{q} \uparrow h^{q}$  as  $\epsilon \downarrow 0$ . Using dominated convergence,

$$-\frac{\mathrm{G}^{\Omega}(h^{q}V)(x)}{h(x)} \geq -\frac{1}{1-q}.$$
(52)

Notice that here  $G^{\Omega}(h^q V_+)(x) < +\infty$ ; otherwise

$$G^{\Omega}(h^{q}V_{\pm})(x) = +\infty,$$

which contradicts the assumption that  $G^{\Omega}(h^{q}V)(x)$  is well-defined.

Clearly, (49) yields the following inequality at x:

$$u \leq h_{\epsilon} \left[ 1 - (1-q) \frac{\mathrm{G}^{\Omega}(h_{\epsilon}^{q} V_{+})}{h_{\epsilon}} + (1-q) \frac{\mathrm{G}^{\Omega}(h^{q} V_{-})}{h} \right]^{\frac{1}{1-q}}.$$
 (53)

By the dominated convergence theorem, we obtain the corresponding upper estimate at x:

$$u(x) \leq h(x) \left[1-(1-q) \frac{\mathrm{G}^{\Omega}(h^q V)(x)}{h(x)}\right]^{rac{1}{1-q}}$$

Since by assumption u(x) > 0, the expression in square brackets must be strictly positive (the desired necessary condition).

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### Extensions of Theorem 3

We continue our discussion of pointwise estimates of solutions in the local case for arbitrary domains  $\Omega \subseteq M$  (not necessarily relatively compact). Denote by  $\partial_{\infty}M$  the infinity point of the one-point compactification of M. For any open subset  $\Omega \subseteq M$  denote by  $\partial_{\infty}\Omega$  the union of  $\partial\Omega$  and  $\partial_{\infty}M$ , if  $\Omega$  is not relatively compact (infinite boundary of  $\Omega$ ). We set  $\partial_{\infty}\Omega = \partial\Omega$  if  $\Omega$  is relatively compact.

#### Definition

For a function  $\boldsymbol{u}$  defined in  $\boldsymbol{\Omega} \subseteq \boldsymbol{M}$ , we write

$$\lim_{\gamma \to \partial_{\infty} \Omega} u(y) = 0, \tag{54}$$

if  $\lim_{k\to\infty} u(y_k) = 0$  for any sequence  $\{y_k\}$  in  $\Omega$  that converges to a point of  $\partial_{\infty}\Omega$ ; the latter means, that either  $\{y_k\}$  converges to a point on  $\partial\Omega$  or diverges to  $\partial_{\infty}M$ . In the same way we understand similar equalities and inequalities involving **lim sup** and **lim inf**.

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#### Local case

For example, if  $\Omega$  is relatively compact, then (54) means that  $\lim_{k\to\infty} u(y_k) = 0$  for any sequence  $\{y_k\}$  converging to a point on  $\partial\Omega$ . If  $\Omega = M$  then  $\partial\Omega = \emptyset$  and (54) means that  $\lim_{k\to\infty} u(y_k) = 0$  for any sequence  $y_k \to \partial_{\infty} M$ , that is, for any sequence  $\{y_k\}$  that leaves any compact subset of M.

In particular, for  $M = \mathbb{R}^n$ , (54) is equivalent to  $u(y) \to 0$  as  $|y| \to \infty$ . We will use the notation

$$\chi_{u}(x) = \left\{ egin{array}{cc} 1, & u(x) > 0, \ 0, & u(x) \leq 0. \end{array} 
ight.$$

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### Main results: local case

### Theorem 4 (Grigor'yan-Verbitsky 2019)

Let (M, m) be an arbitrary weighted manifold. Let  $\Omega \subseteq M$  be a connected open subset of M with a finite Green function  $G^{\Omega}$ . Suppose  $V, f \in C(\Omega)$ , where  $f \geq 0, f \not\equiv 0$  in  $\Omega$ . Let  $u \in C^2(\Omega)$  satisfy

in the case 
$$\boldsymbol{q} > \boldsymbol{0}: -\Delta \boldsymbol{u} + \boldsymbol{V} \boldsymbol{u}^{\boldsymbol{q}} \geq \boldsymbol{f}$$
 in  $\Omega, \ \boldsymbol{u} \geq \boldsymbol{0},$  (55)

or

in the case 
$$q < 0$$
:  $-\Delta u + V u^q \leq f$  in  $\Omega$ ,  $u > 0$ . (56)

Set  $h = G^{\Omega} f$  and assume that  $h < \infty$  in  $\Omega$ . Assume also that  $G^{\Omega}(h^{q}V)(x)$  (respectively  $G^{\Omega}(\chi_{u}h^{q}V)(x)$  in the case 0 < q < 1) is well-defined for all  $x \in \Omega$ .

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# Main results: local case (continuation)

Theorem 4 (statements (i)-(ii)) Then the following statements hold for all  $x \in \Omega$ . (i) If q = 1, then  $u(x) \ge h(x)e^{-\frac{1}{h(x)}G^{\Omega}(hV)(x)}$ .

(ii) If q > 1, then necessarily

$$-(q-1) \operatorname{G}^{\Omega}(h^{q} V)(x) < h(x), \qquad (58)$$

and the following estimate holds:

$$u(x) \geq \frac{h(x)}{\left[1 + (q-1)\frac{G^{\Omega}(h^{q}V)(x)}{h(x)}\right]^{\frac{1}{q-1}}}.$$
 (59)

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(57)

# Main results: local case (continuation)

Theorem 4 (statements (iii)-(iv)) (iii) If 0 < q < 1, then  $u(x) \geq h(x) \left| 1 - (1-q) \frac{\mathrm{G}^{\Omega}(\chi_u h^q V)(x)}{h(x)} \right|^{\frac{1}{1-q}}.$ (60)(iv) If q < 0 and  $\lim_{y \to \partial_{\infty} \Omega} u(y) = 0$ , then necessarily (58) holds, and  $u(x) \leq h(x) \left[1-(1-q)\frac{\mathrm{G}^{\Omega}(h^{q}V)(x)}{h(x)}\right]^{\overline{1-q}}.$ (61)

**Remarks.** 1. Condition  $f \not\equiv 0$  implies  $h = G^{\Omega} f > 0$  in  $\Omega$ . 2. No *boundary conditions* are imposed in the case q > 0.

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# Remarks

(continuation)

**Remarks.** 3. In the case  $q \ge 1$ , it follows from (57) and (59) that the condition

 $G^{\Omega}(h^{q} V)(x) < +\infty$ 

implies u(x) > 0. Moreover, if for some  $0 < C < \frac{1}{q-1}$  and all  $x \in \Omega$ ,

 $\mathrm{G}^{\Omega}\left(h^{q}V\right)\left(x
ight)\leq Ch\left(x
ight),$ 

then  $u \ge c h$  in  $\Omega$  with some constant c = c(C, q) > 0.

4. In the case 0 < q < 1, the function u can vanish in  $\Omega$ , but the estimate of u does not depend on the values of V on the set  $\{u = 0\}$ . This explains the appearance of the factor  $\chi_u$  and the subscript + on the right-hand side of (60).

5. In the case q < 0, the boundary condition  $\lim_{y \to \partial_{\infty} \Omega} u(y) = 0$  is essential; without it u does not admit any upper bound.

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# Main results: local case (continuation)

The proof of Theorem 4 reduces to Theorem 3 above that deals with relatively compact sets  $\Omega \subset M$ , using an exhaustion of  $\Omega = \bigcup_{k=1}^{\infty} \Omega_k$  by means of increasing relatively compact sets  $\Omega_k$  with smooth boundary, and approximation of f. We omit the details (see [Grigor'yan-Verbitsky 2019], Proof of Theorem 3.1).

In the next theorem we give estimates of solutions u of semi-linear inequalities (55)-(56) with  $f \equiv 0$ . (Theorem 4 requires that  $f \not\equiv 0$ .) Such results are applicable to the so-called gauge function for Schrödinger equations (q = 1), large solutions for super-linear equations (q > 1), or ground state solutions ( $-\infty < q < 1$ ) to the corresponding equations and inequalities in unbounded domains in  $\mathbb{R}^n$  or on noncompact manifolds.

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